

Neoclassical Tearing Mode Control by Electron Cyclotron Current Drive Using Dynamic Alignment to Access Higher Performance

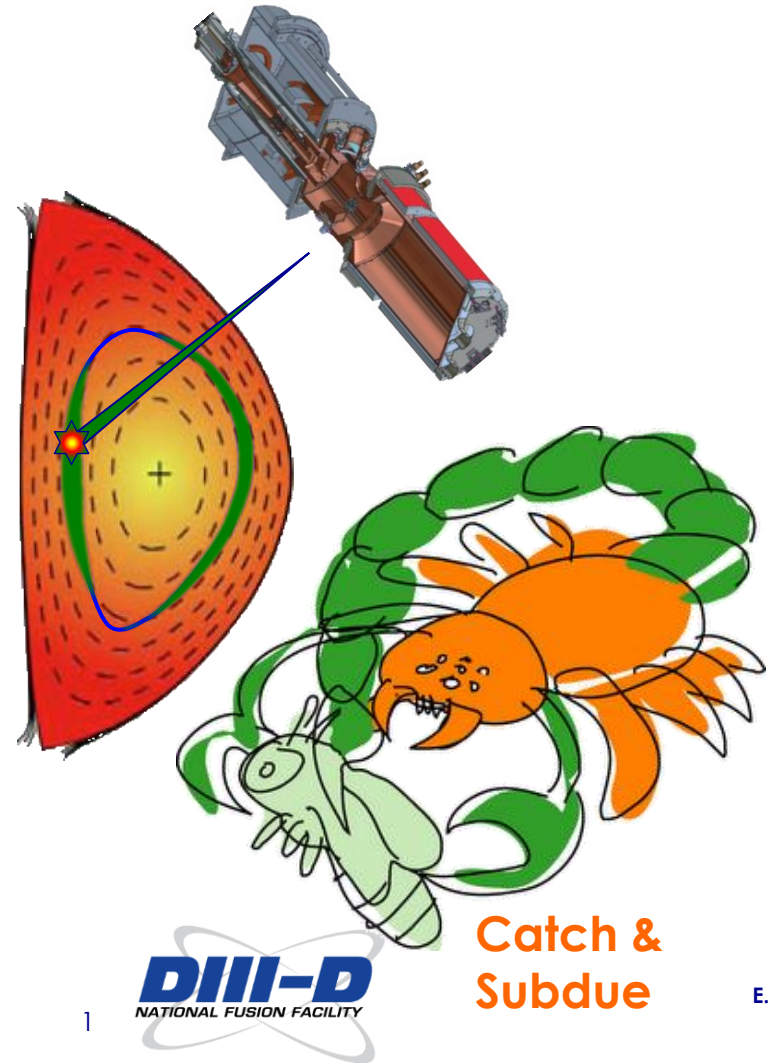
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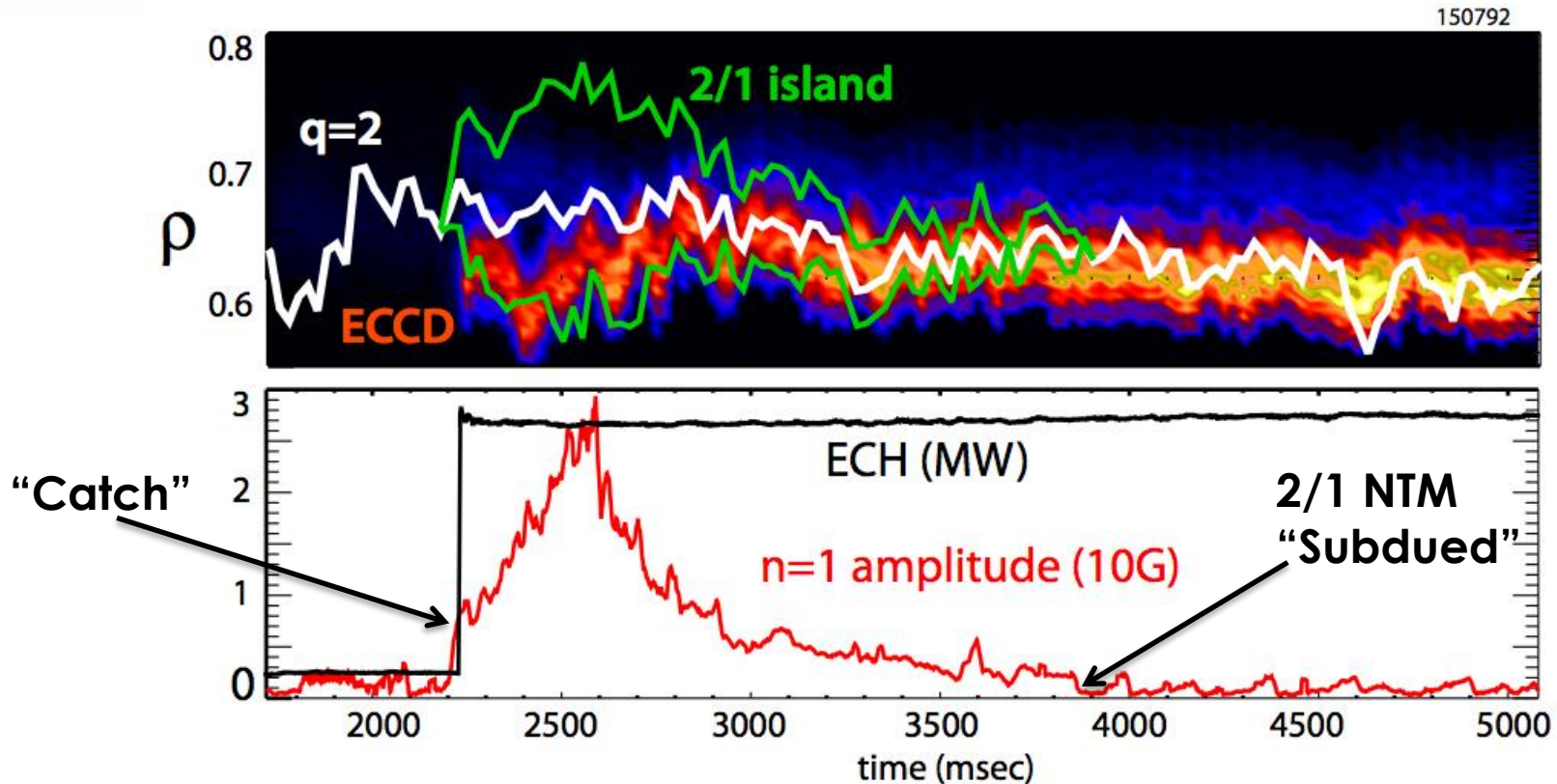
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Presented at XX RF Conference, June, 2013



Fully Automatic NTM Control Using Real-Time Mirror Steering Can Suppress the 2/1 Mode

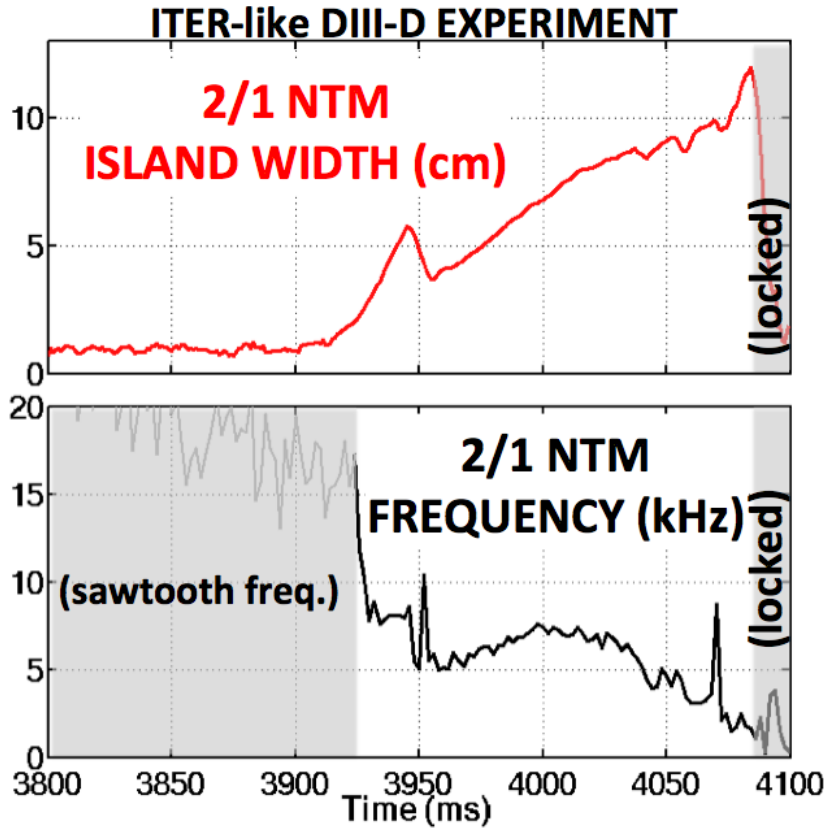


- New fully automatic NTM control system at DIII-D integrates all the Real-Time (RT) components of mode detection, location, suppression.
- New control strategy "Catch and Subdue" can reduce the EC power use; lead to higher Q and reduce disruption risk in ITER

In ITER, without ECCD, 2/1 Islands Can Grow, Lock and Cause Disruptions

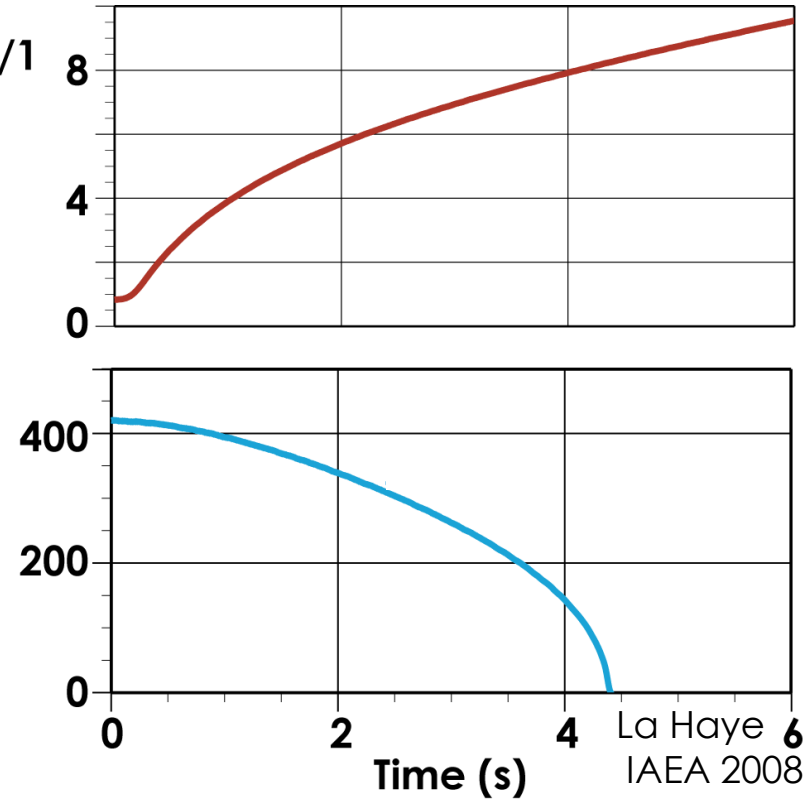
DIII-D experiment

ITER Simulation



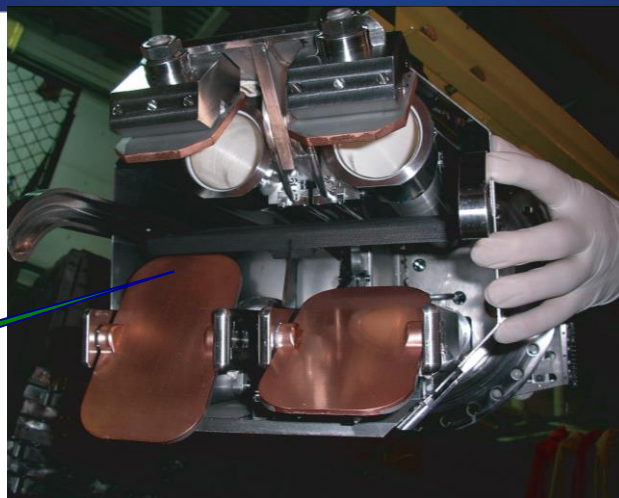
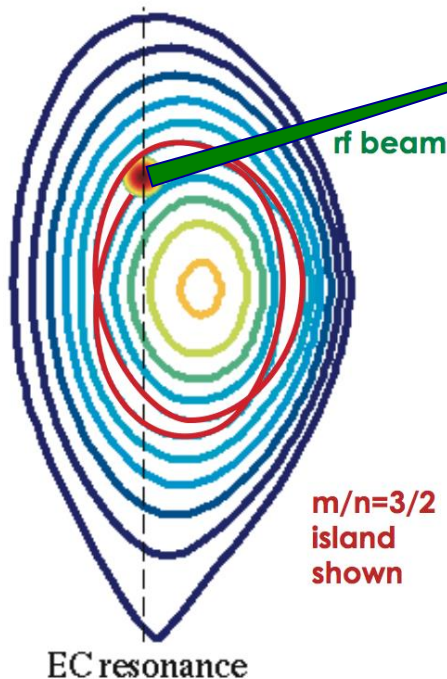
$m/n = 2/1$
Island
Full
Width
 w
(cm)

$q = 2$
Plasma
Rotation
(Hz)

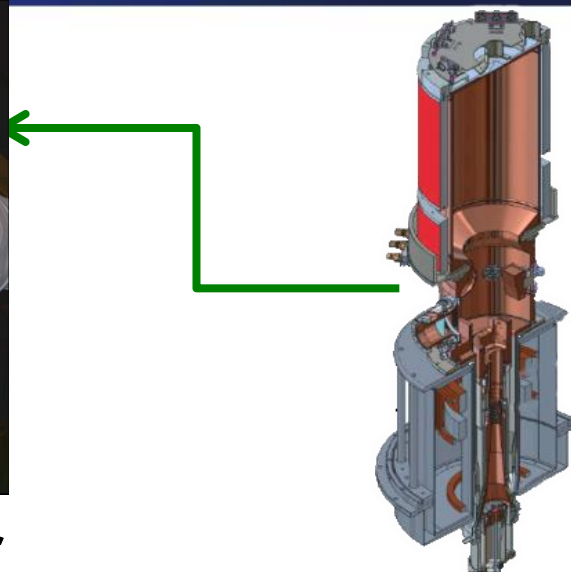


- Loss of H-mode and disruption is expected after locking
- Need robust and efficient NTM control strategies

Accurate Alignment of ECCD to Resonant Surface Suppresses Neoclassical Tearing Mode



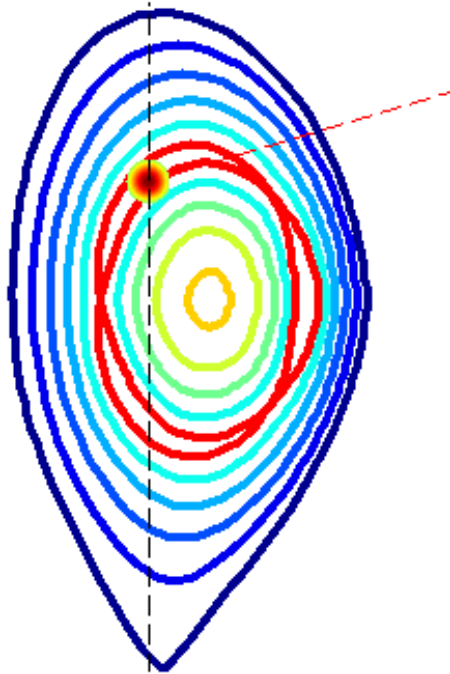
Steerable Launcher Mirror



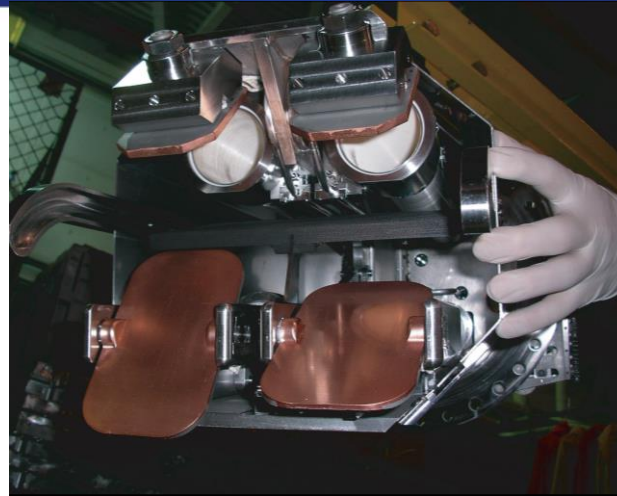
**5 Gyrotrons
(~2.8 MW injected)**

- Align the **Electron Cyclotron Current Drive** deposition with the **Neoclassical Tearing Mode (NTM) island** for suppression
- Mirrors steered to move the beam vertically along the EC resonance for best alignment

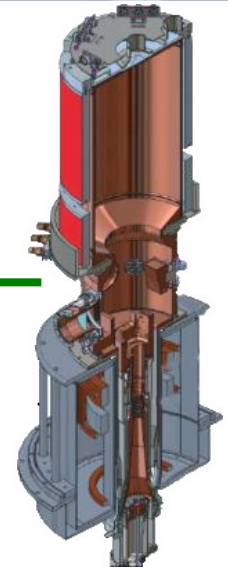
Accurate Alignment of ECCD to Resonant Surface Suppresses Neoclassical Tearing Mode



EC resonance



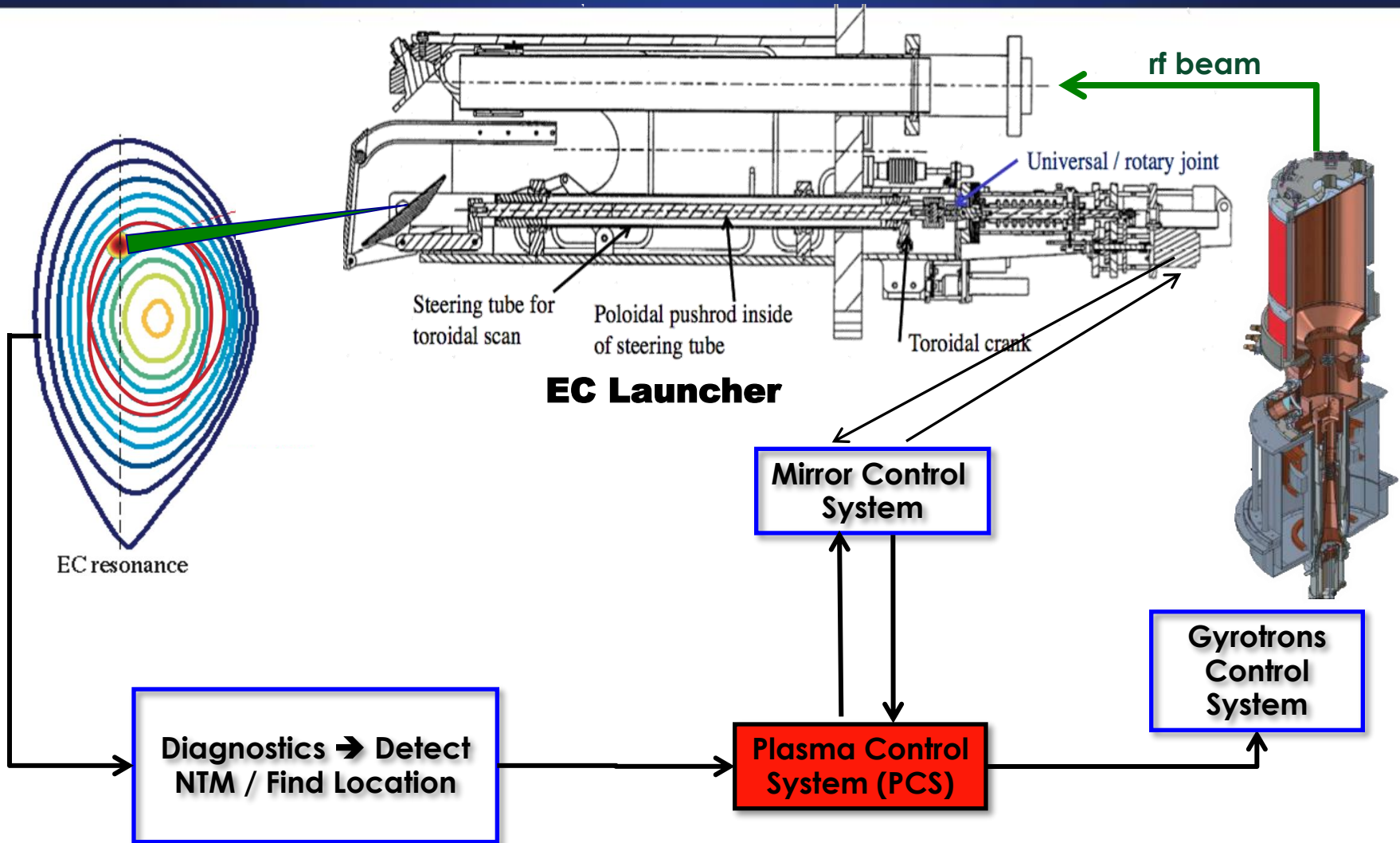
Steerable Launcher Mirror



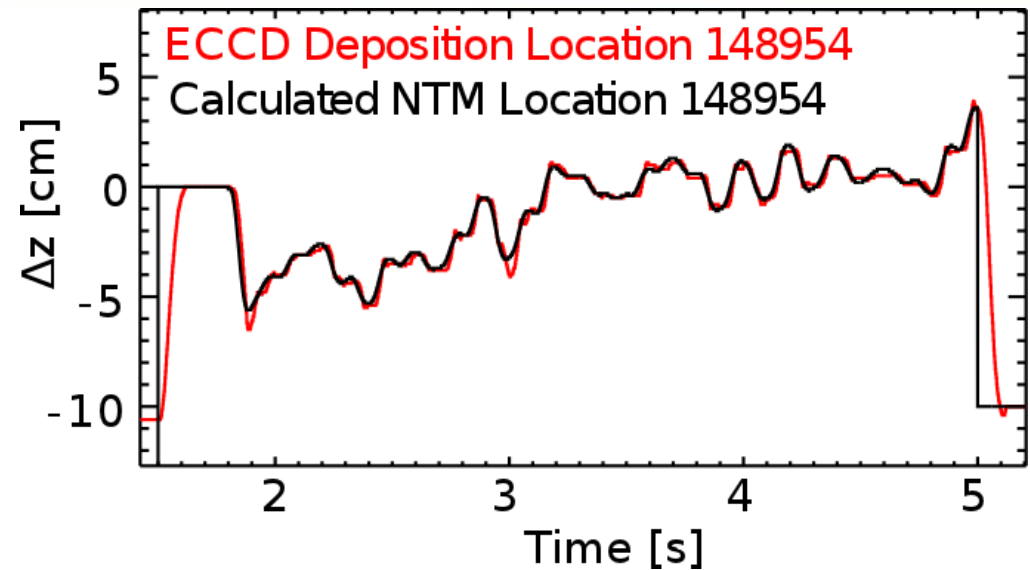
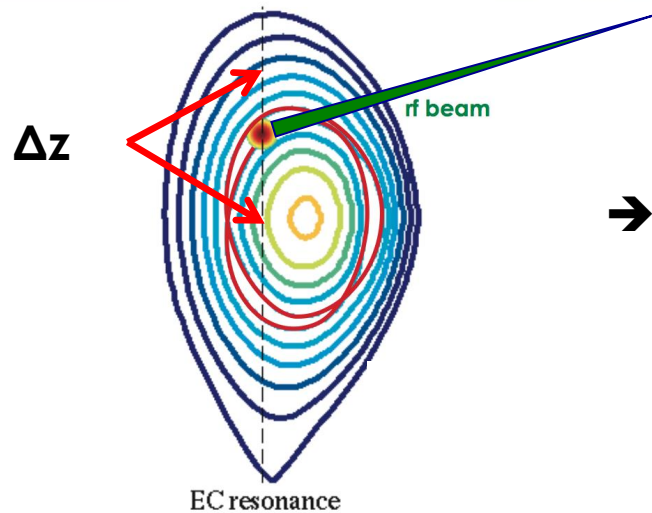
**5 Gyrotrons
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- Align the **Electron Cyclotron Current Drive** deposition with the **Neoclassical Tearing Mode (NTM) island** for suppression
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DIII-D NTM Control System Overview



Real time MSE Equilibria Enable Precise Tracking of Resonant Surface

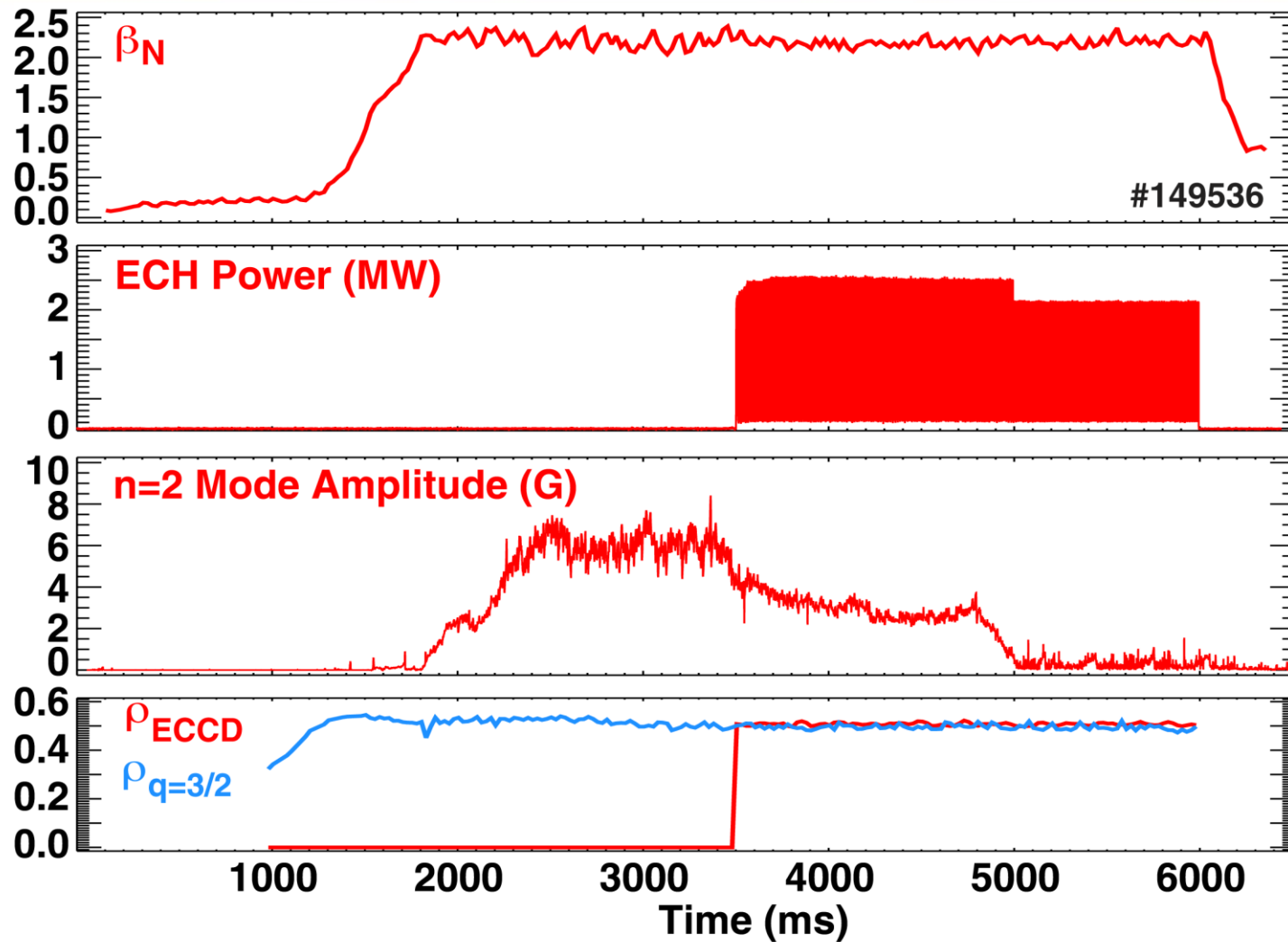


- Real time MSE tracks $q=3/2$ or 2
- Calculate intersection point of the q surface with $2f_{ce}$
- Move the mirrors to align the ECCD with NTM
- Tracking performance with minimal overshoot and <1 cm error.
- Calibration:
 - *ECCD deposition: with 100 Hz ECCD modulation*
 - *NTM location: with ECE based calculation & Sweeps across NTM*
 - *Mapping of angle in mirror to position in plasma: Ray tracing*

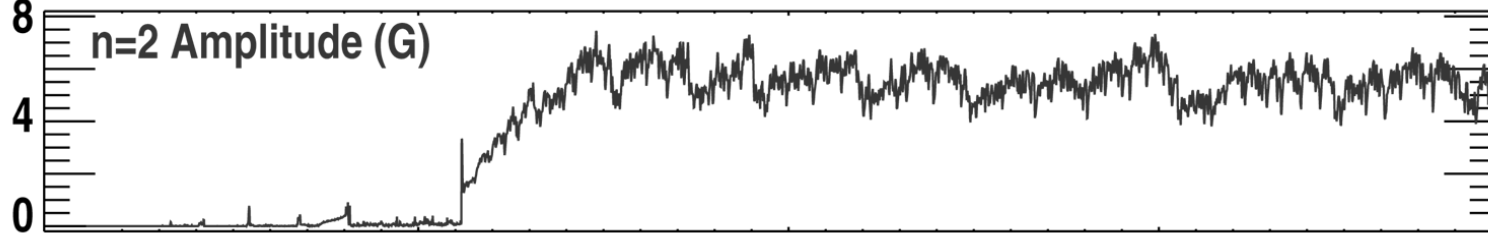
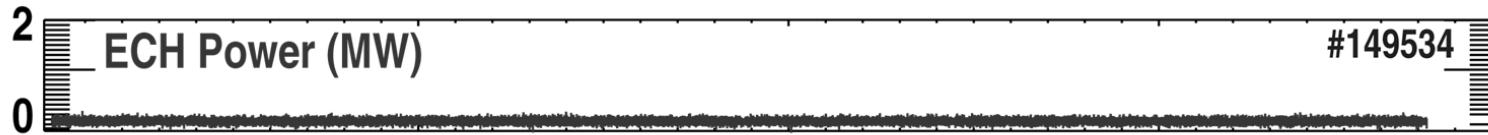
Application to the 3/2 NTM:

- Head room to develop the technique

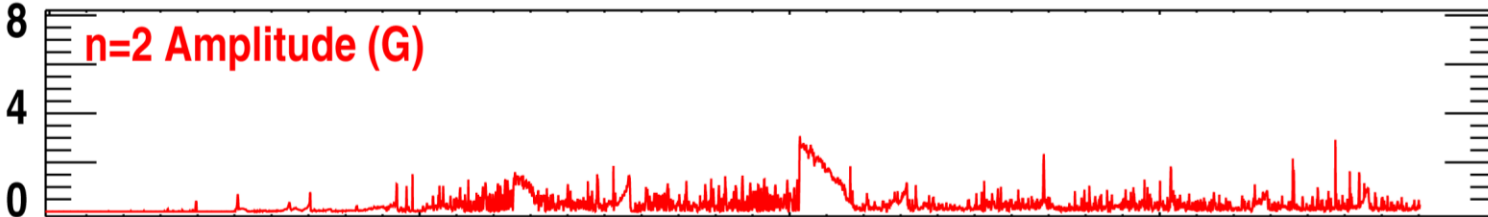
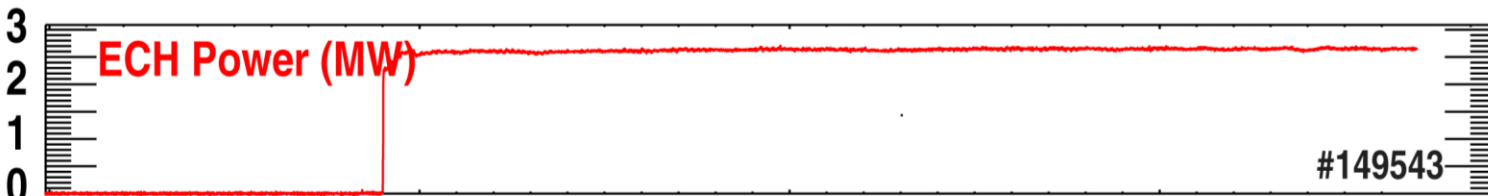
NTM Control Methods: Successful 3/2 NTM Suppression After Mode Saturation



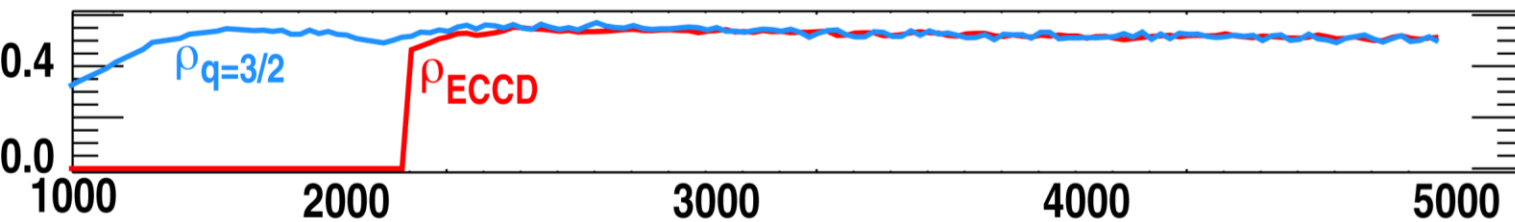
NTM Control Methods: Preemptive NTM Suppression Achieved



Without
ECCD, 3/2
NTM
develops

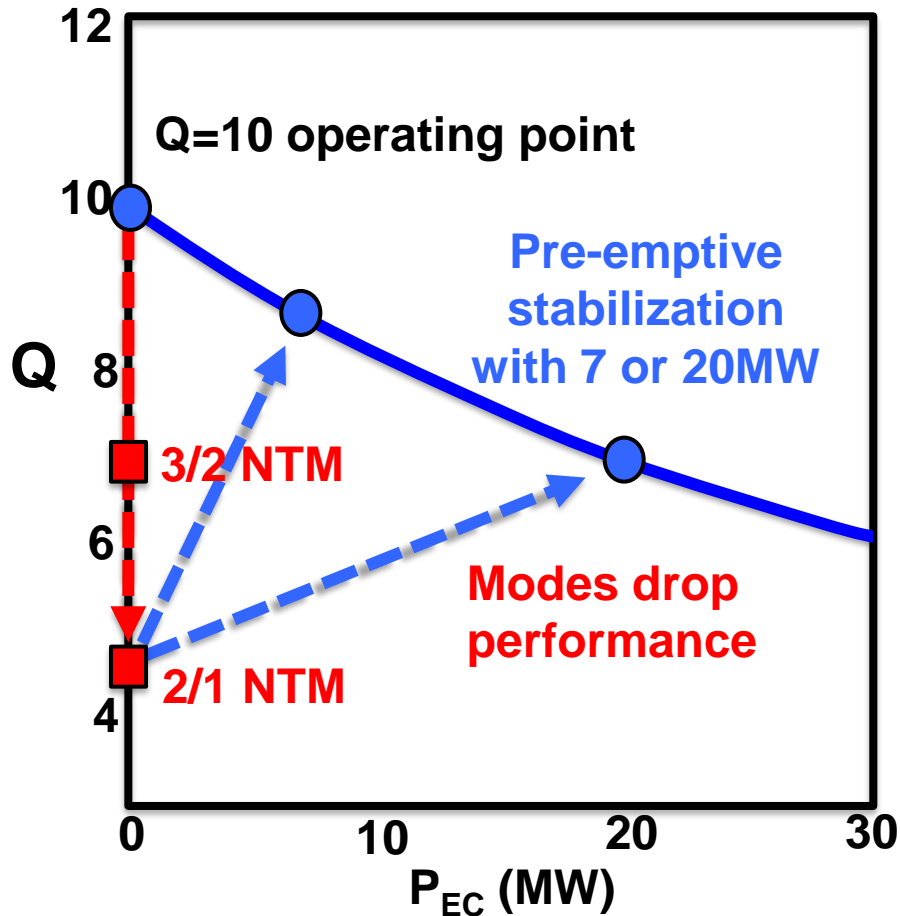


NTM
Preemption
with ECCD



Minimize EC Use for Higher Q Operation

Pre-emptive suppression



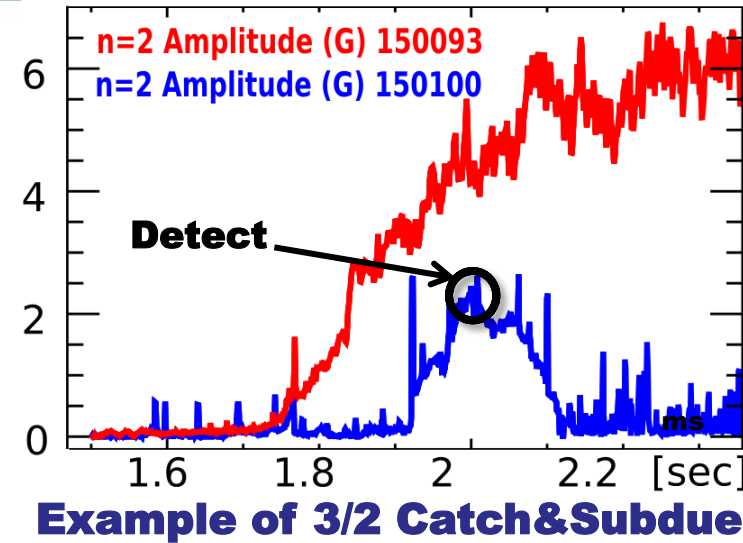
- **ITER strategies:**

- **Preemptive suppression:** uses continuous power, decreases Q
- **Suppression after saturation:** requires large power and long time, risking disruptions
- **Preferable to intercept mode while still small**

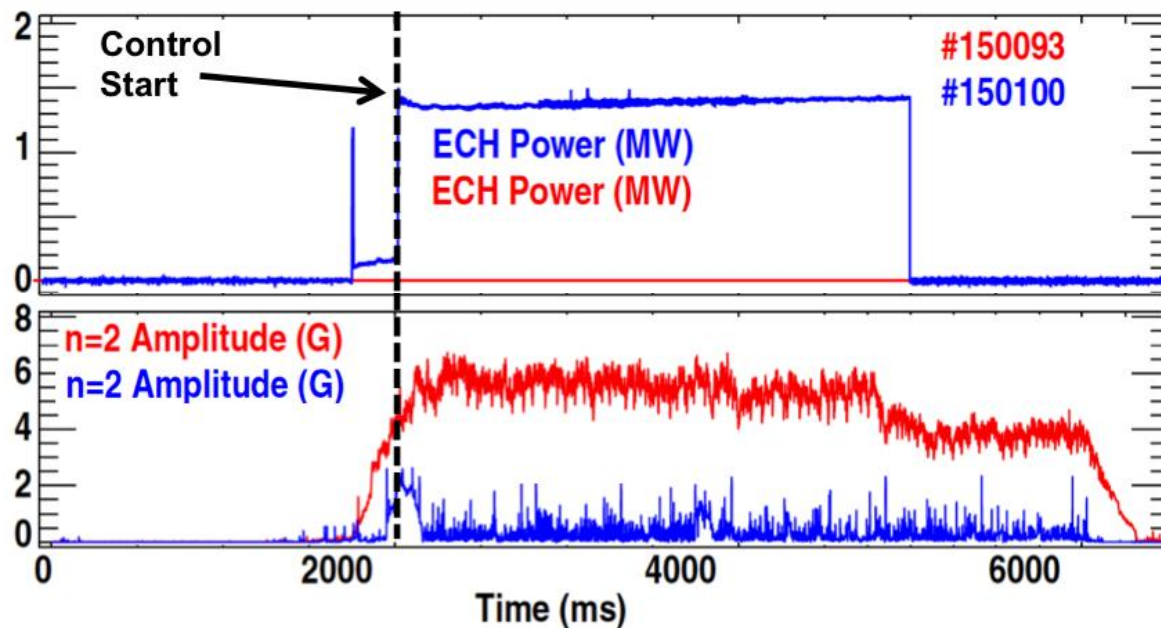
[Zohm, IAEA 2006]

New "Catch and Subdue" Technique is More Efficient

- **Continuous q-surface Following**
 - Constantly calculate q-surface in plasma
 - Track w/ mirrors and be ready to suppress
- **Detect that island is forming (2/1 or 3/2)**
 - Real-time Fourier analysis of Mirnov diagnostics
- **Turn Gyrotrons ON when the mode is detected**
- **Result: Catch the island before it saturates**
 - Island saturation for 2/1 mode ~100-150 ms, 3/2 mode ~200ms



Catch and Subdue Technique Enables Much Faster Suppression and Reduced ECCD Power



150093: No ECCD
(Beam drops after 5 sec)

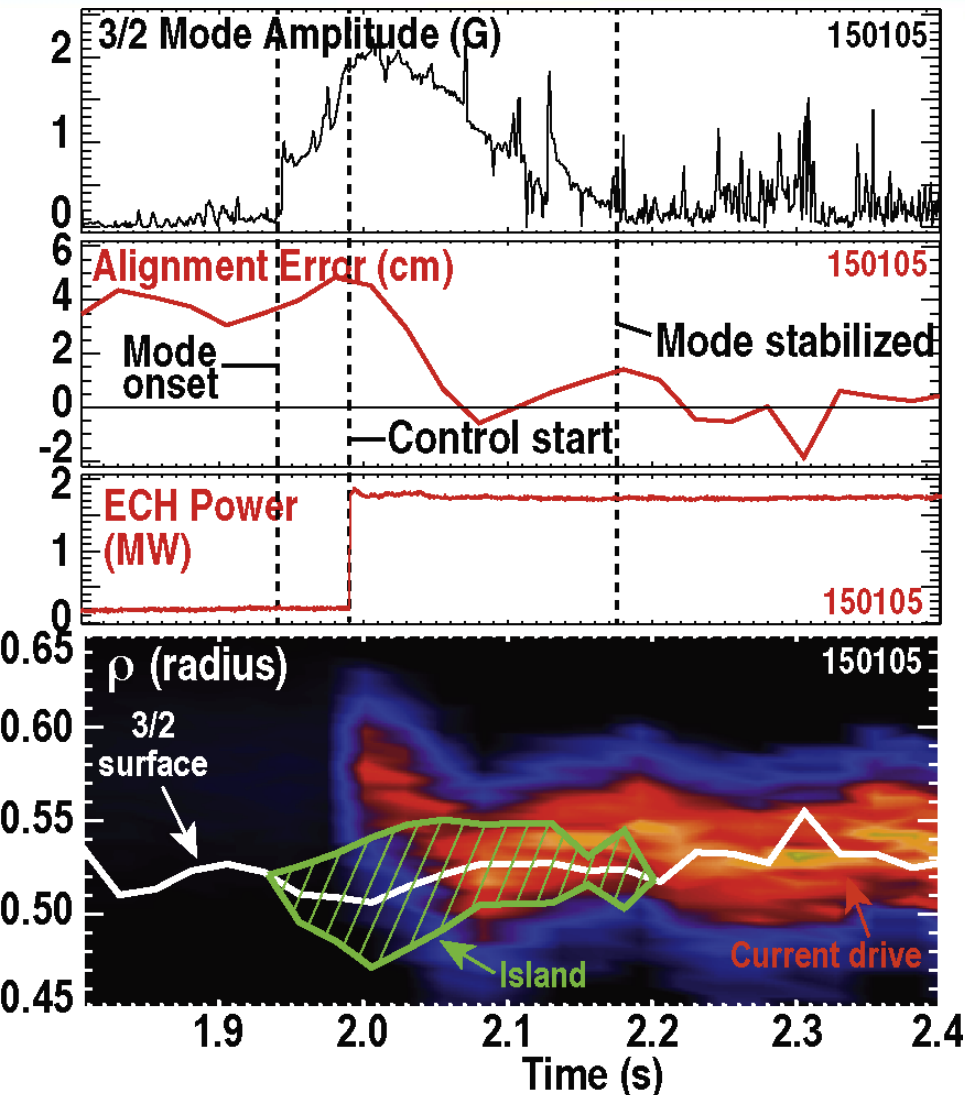
150100: Catch and Subdue
(Many more examples)

Results:

- *Less power needed: Suppression with 3 gyrotrons instead of 5 for fully saturated modes*
- *Faster suppression (~140 ms after the gyrotrons turn on)*
- *Avoids continuous power deposition of the preemptive approach*

Catch and Subdue Even Works Well

Starting from Intentional Misalignment of ECCD and q Surface



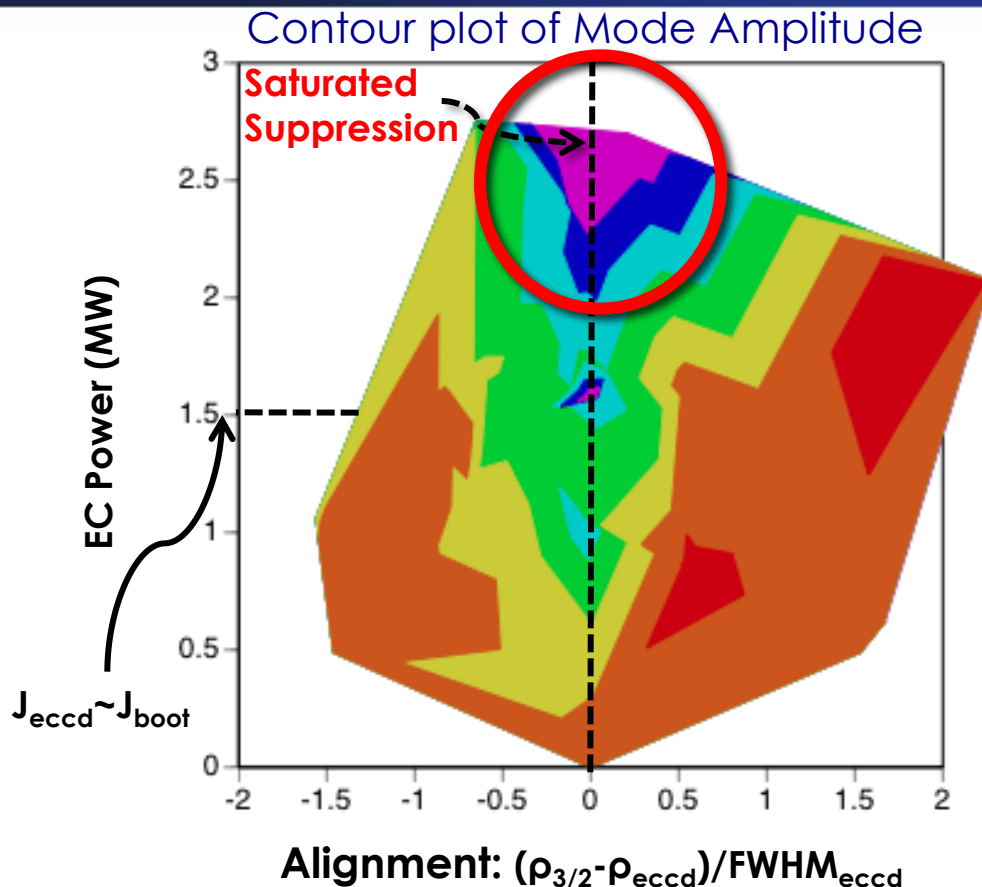
Experiment:

- Intentional mirror misalignment ~ 4 cm

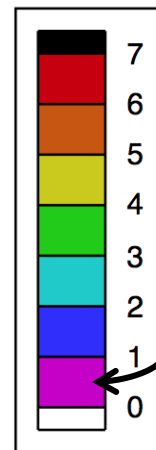
Result:

- System rapidly corrects deposition location
- Fast suppression: complete suppression takes ~ 40 ms longer than aligned case

Saturated Mode Suppression of 3/2 NTM Requires Good Alignment & $J_{\text{eccd}} > J_{\text{boot}}$



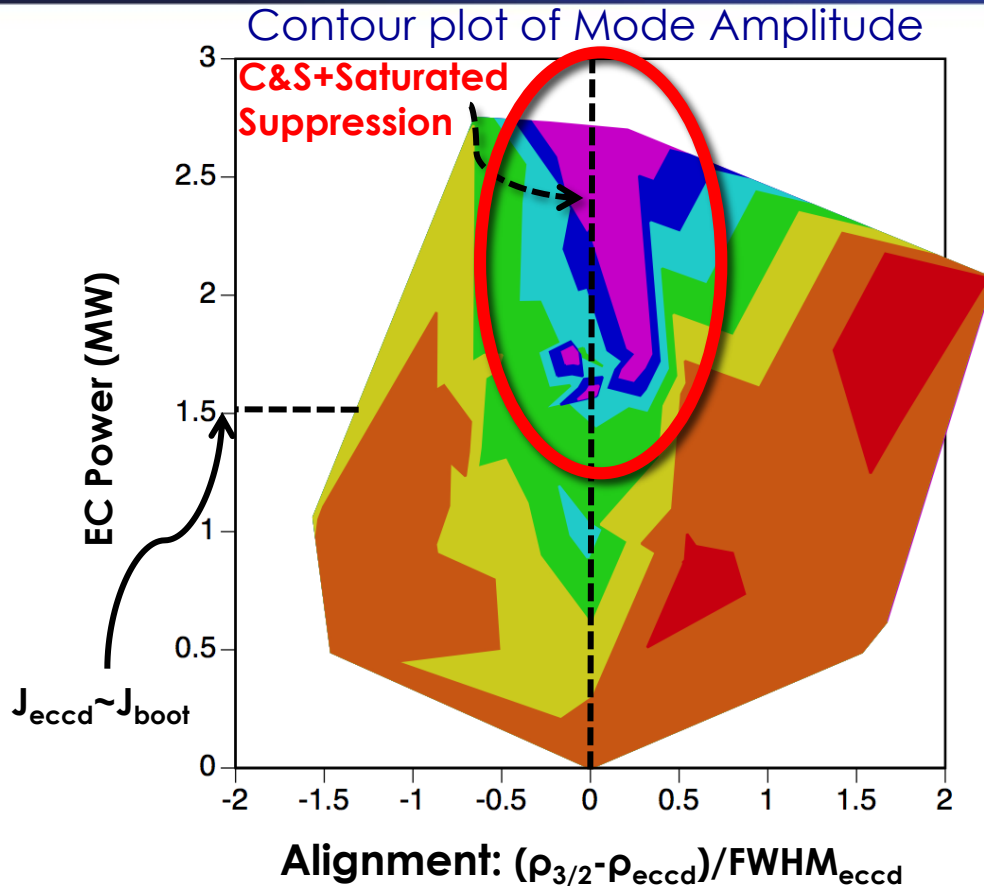
Color=Mode amplitude (Gauss)



No mode

1. Power: Peak ECCD (J_{eccd}) > local bootstrap current density (J_{boot})
 \rightarrow To replace the missing current in the island.
2. Alignment: ECCD aligned with the 3/2 island within the half width of the ECCD profile

Catch and Subdue Needs Less Power



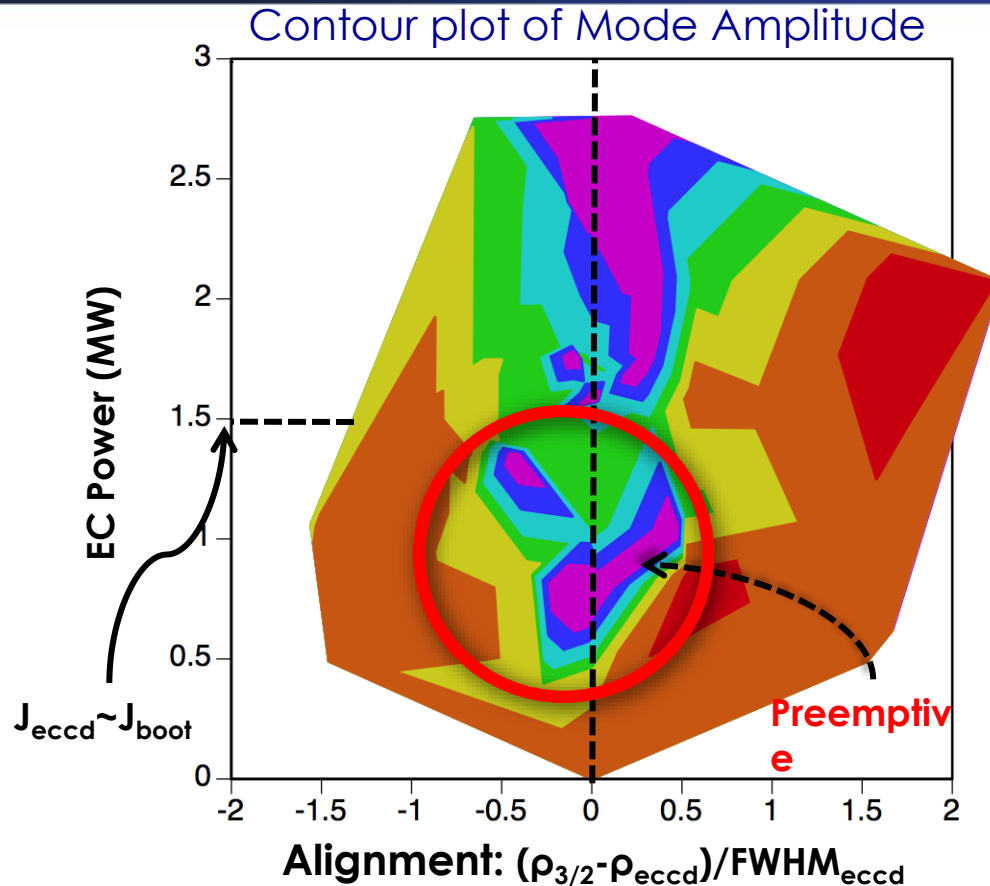
Color=Mode amplitude (Gauss)



No mode

- Catch and Subdue needs less power compared to saturated mode suppression.

Preemptive ECCD Reduces Power Requirement for 3/2 Suppression by Over 50%



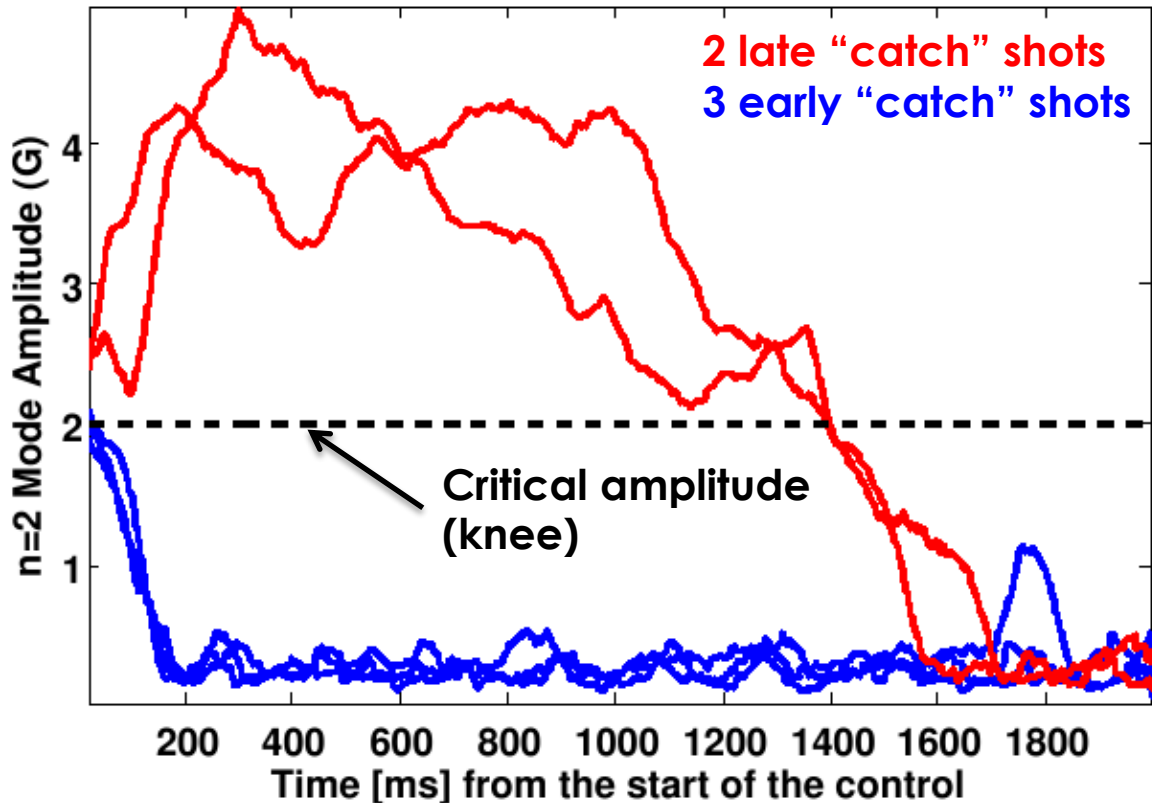
Color=Mode amplitude (Gauss)



No mode

- Preemption reduces the power threshold.

Early Mode Detection is Key for Rapid NTM Suppression



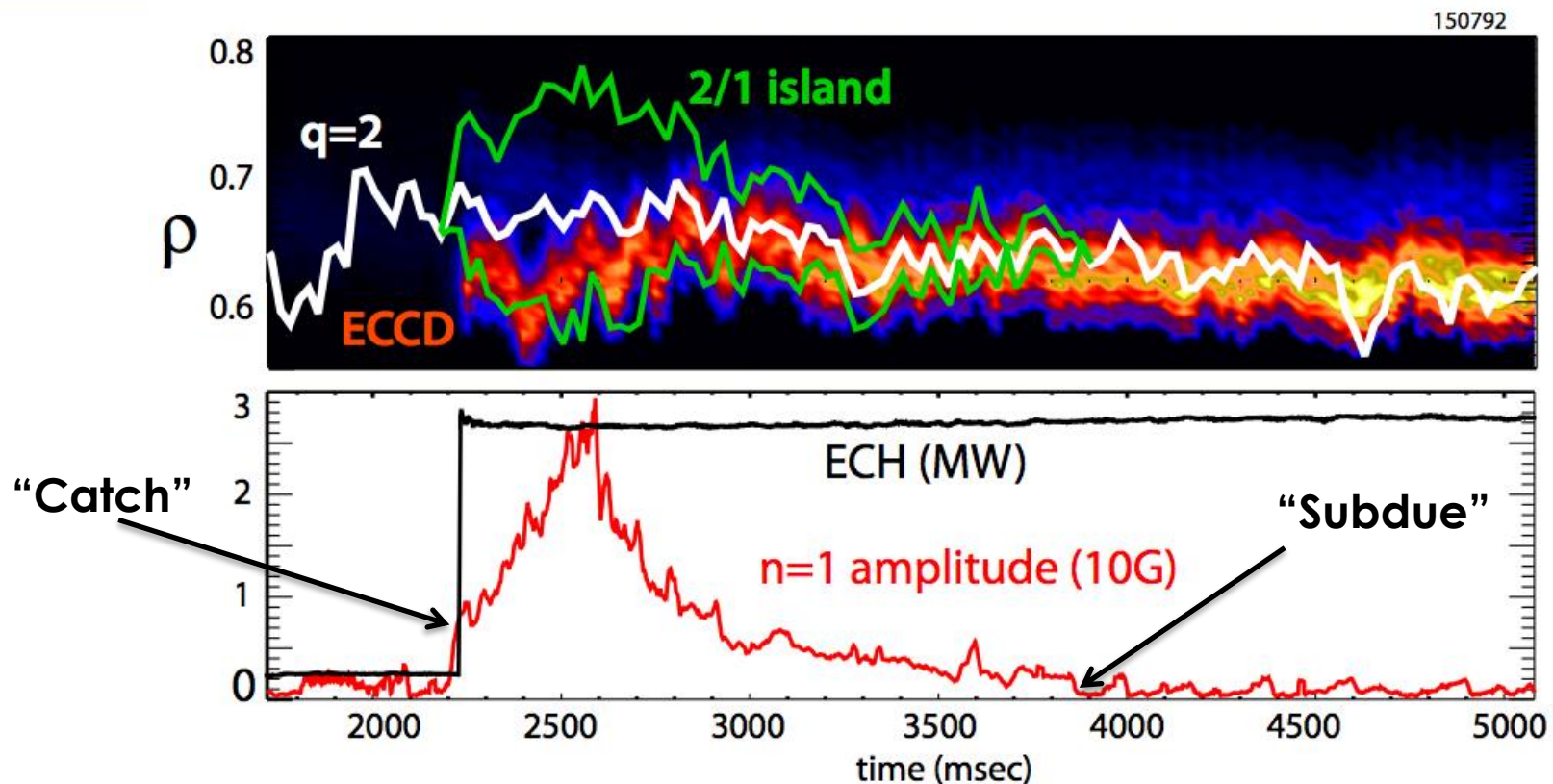
- **Below the critical amplitude** *small island effect takes over which enable fast suppression*
- **Above the critical amplitude** *the mode saturates and suppression takes more than a second or becomes unachievable*

*All shots with same β_N and ECCD is actively aligned with a power of 1.5 ± 0.2 MW at the island location.

Application to the 2/1 NTM:

- Most challenging and important case

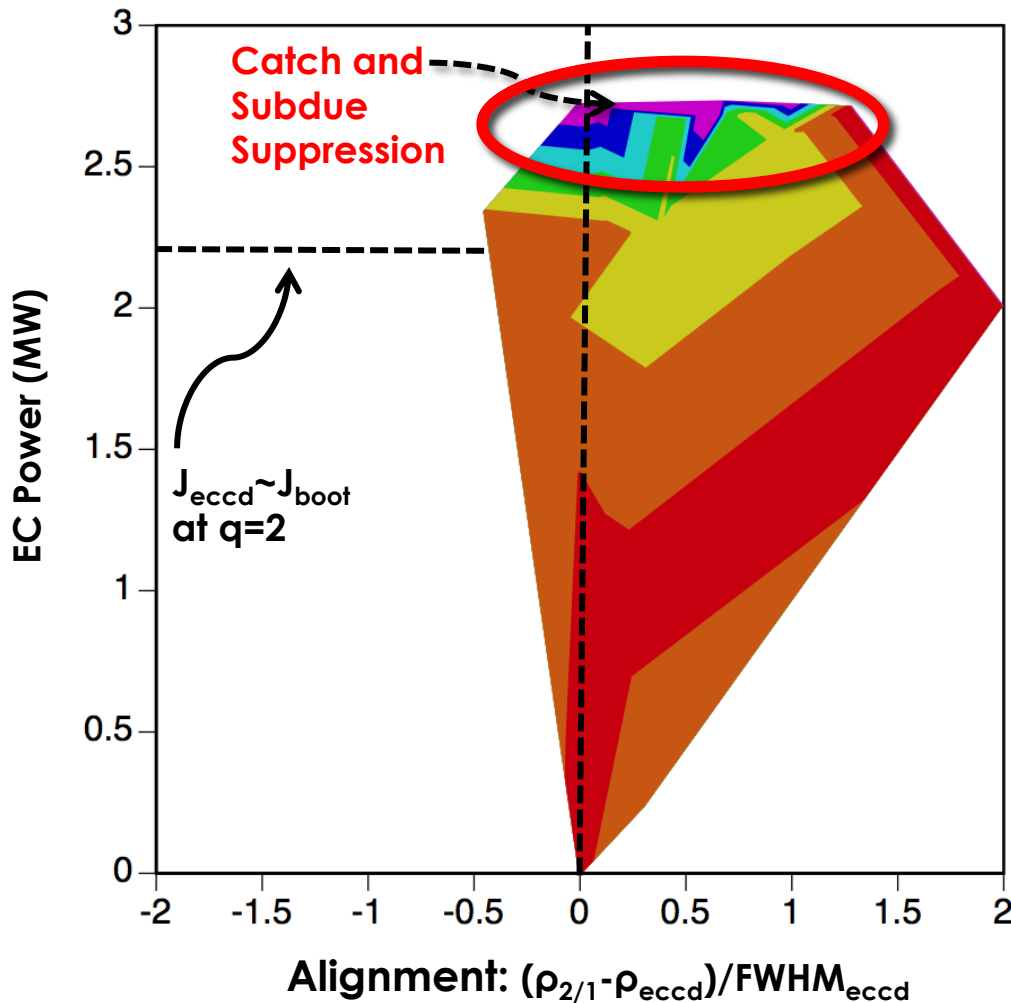
Successful 2/1 NTM Catch and Subdue Demonstrated



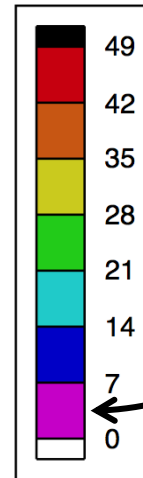
- Peak mode amplitude is reduced; without ECCD, mode reaches ~ 40 G and locks with loss of H-mode
- The mode is brought to full suppression

2/1 Mode Suppression Requires Good Alignment & $J_{\text{eccd}} > J_{\text{boot}}$

Contour plot of Mode Amplitude



Color=Mode amplitude (Gauss)



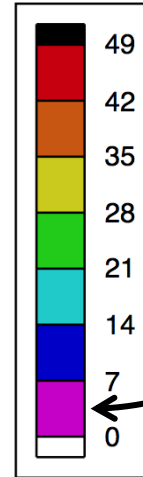
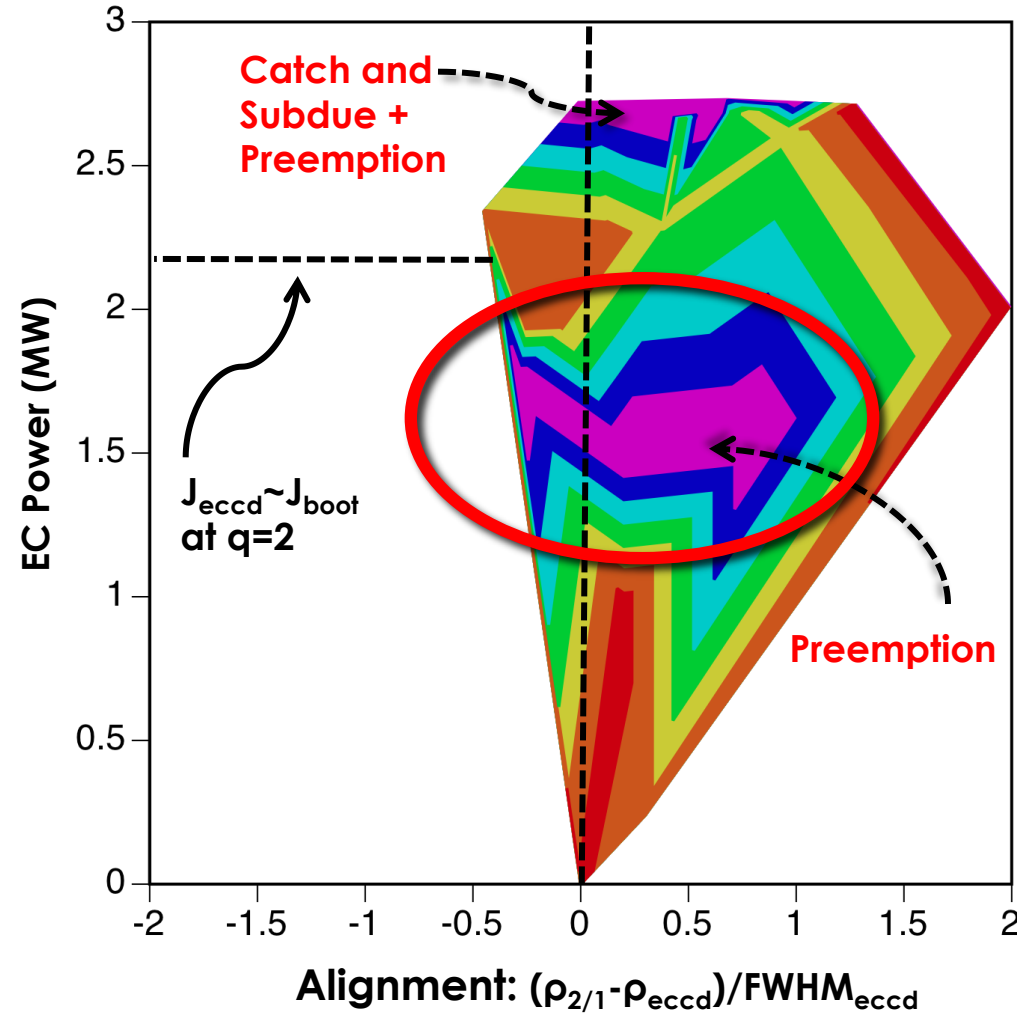
No mode

- No cases of Saturated Suppression
- Catch & Subdue suppression of 2/1 pushes the limit of the available EC power

Preemptive ECCD Reduces Power Requirement for 2/1 Suppression by 40%

Contour plot of Mode Amplitude

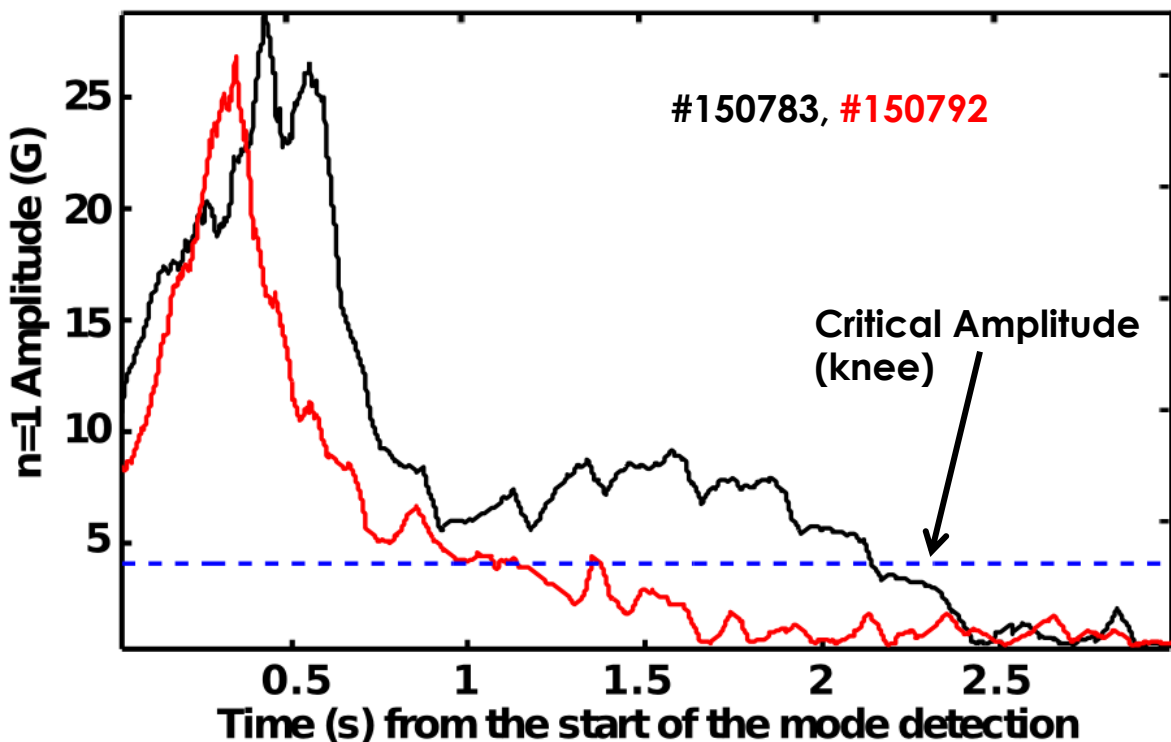
Color=Mode amplitude (Gauss)



No mode

- Preemption reduces the power threshold.

Faster Suppression Needs Early Mode Detection for “Catch and Subdue”

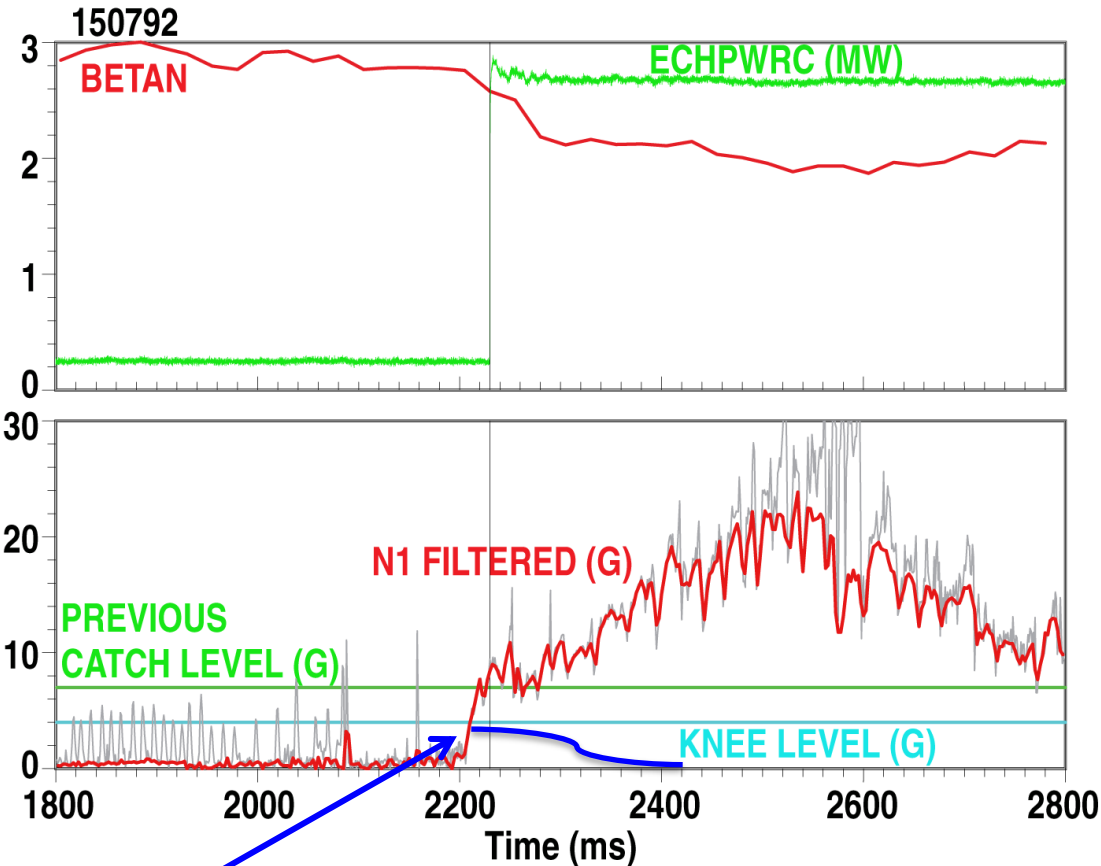


- Islands caught bigger than the critical amplitude takes much longer to suppress
- Noise from sawteeth, fishbones and ELMs are hindrance for small island detection
 - Also important for ITER
- Detection below the critical amplitude would reduce the energy even lower

New Capabilities for 2013:

- Improvements to the Catch Subdue

Better Mode Detection Enable Early Catch



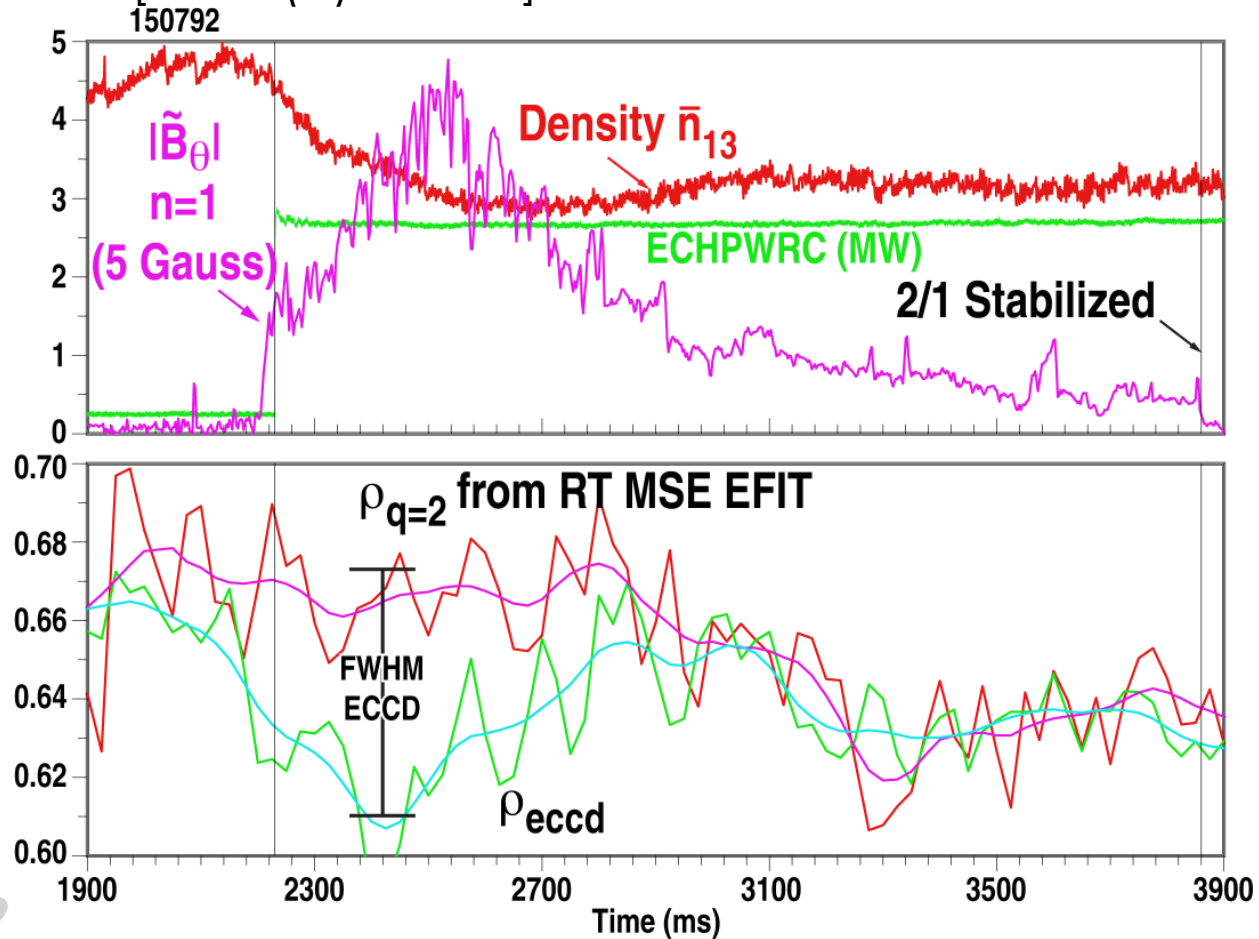
**NEW CATCH LEVEL AND
EXPECTED MODE TRAJECTORY**

- Improved band-pass filtering for mode detection
- Reduce catch level from > 7 Gauss below critical “knee” level of ≈ 4 Gauss for “help” from small island effects
- Faster mode suppression with reduced peak amplitude and shorter time to stabilize

Need for Improved Refraction Algorithm: When EC Turned On, Density Drops, Refraction Changes

- 2012: A simple linear algorithm with n used to redirect mirrors alignment off initially due to *transient density profile change*

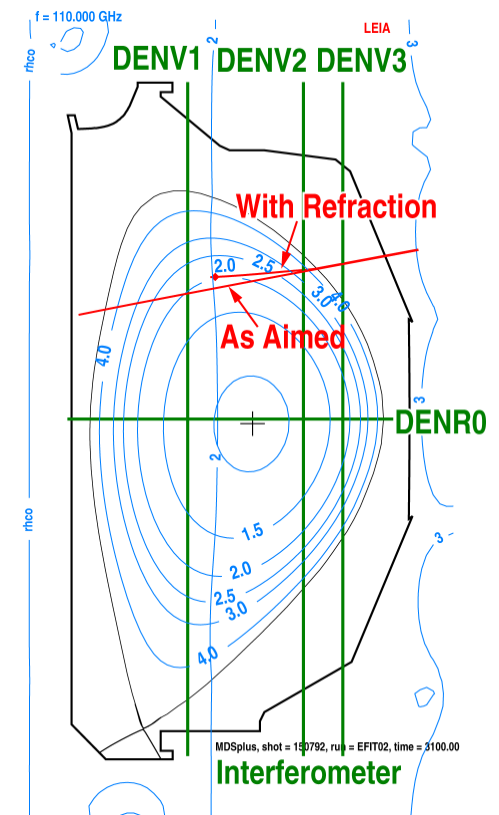
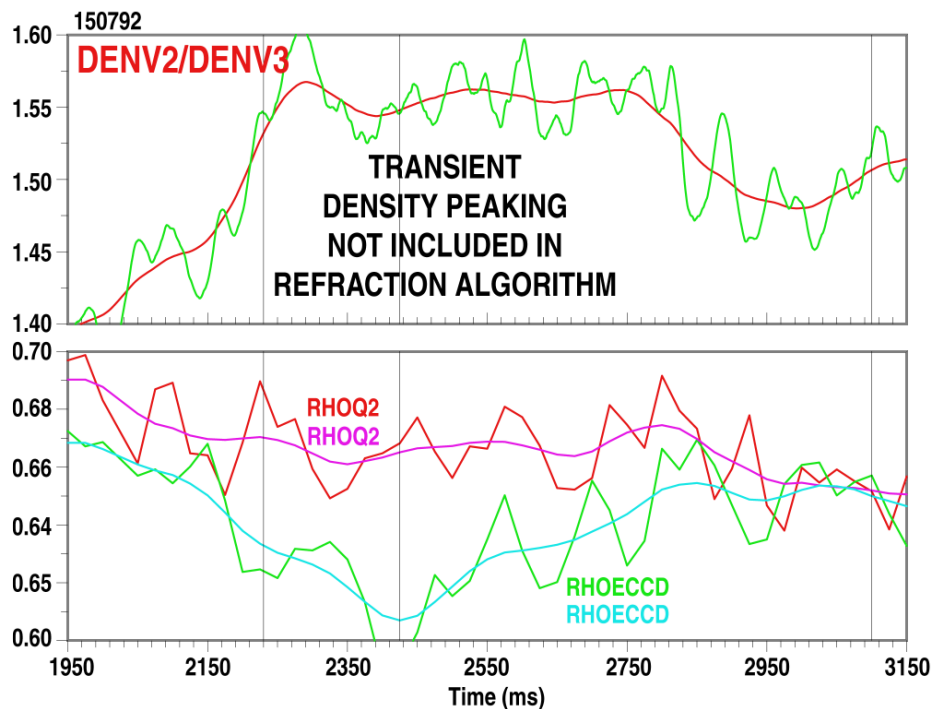
– $dz_{\text{eccd}} = 0.4273 * [\text{denr0}(V) - 0.3599]$ meters



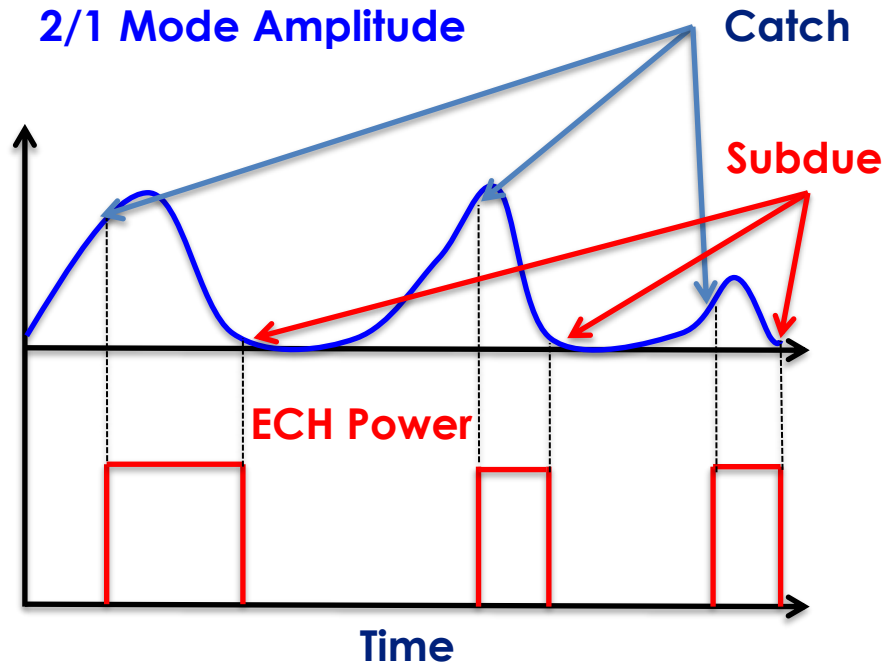
Improved Refraction Algorithm Enables Better Alignment

- 2013:

- Real-time Thomson (42 chan.) density profile calc. implemented
- Real-time Torbeam and a Snell's Law based code being tested
- Mirrors will be given better directions for tracking



Multiple Catch & Subdue Suppress Cycles with Improved PCS



- **Aim:**
 - Reduce the Average EC Power
 - Study the reappearance time scales
- **Method:**
 - Turn on the ECCD when the mode is detected
 - Turn off the ECCD when the mode is suppressed
 - Wait for another mode to appear

Additional Improvements to be Made in 2013 Campaign

- **Increased number of gyrotrons and thus EC power**
 - 5 in 2012 → 6 in 2013 (2.85MW → 3.5MW injected)
- **More robust mirror operations (hardware/software upgrade)**
 - New mirror motors (~3x faster), encoders control boards
 - 100-200 ms to move the mirrors from center to $q=2$
 - Enable multiple mode suppression and central heating while suppressing NTMs.
- **Real-time ECE diagnostic for better identification of location of $q=2$ surface of island to be used to augment real-time MSE EFIT which was used in 2012 and is basis for active tracking without mode**

Integration of NTM Control Elements Is Demonstrating the Ability to Efficiently Control NTMs in ITER

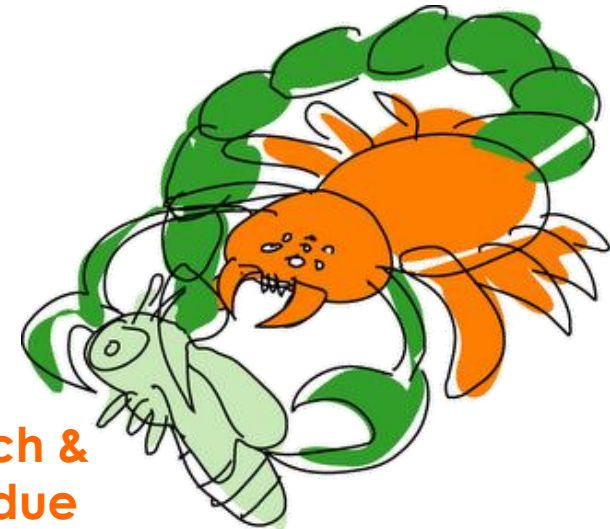
- **Advanced integrated control:**

- Mode detection with Fourier analysis of the Mirnov diagnostics
- Real-time high accuracy equilibrium reconstruction with MSE
- Fast EC steerable mirrors
- Fully automatic control algorithm “catch and subdue” that fuses all the ingredients.

- **Provides an efficient approach for ITER**

- Reduces power requirements for NTM control
- Reduces time to suppress modes
- Decreases adverse effects on confinement & disruption
- Enables higher Q in ITER

- **New capabilities enhances the operations for 2013 campaign**



Catch &
Subdue